Powering the Blue Economy[™] OCEAN OBSERVING P R I Z E

Self-Recharging AUV with SR-WEC

Description	An AUV embodies a customized Surface Riding Wave Energy Converter (SR-WEC) to achieve the self-recharge without any difficulties and problems related to multi-body approaches. During the recharge, the AUV is designed to have 2 peaks in the pitch motion: one is pitch resonance and the other is amplification by the coupled heave resonance. The SR-WEC effectively generates the power from the	
Team	sliding magnet resulting from pitch mot After the recharge, the AUV carries out o using a buoyancy engine, wings, and ru Dr. HeonYong Kang, Assistant Professo	descending and ascending profiling dders.
	Cody Marquardt, A PhD Student A New MS Student joining in June A group of Undergraduate from Ocean Robotics Team joining in March All Members are in Department of Ocean Engineering at Texas A&M University	
Dry Weight	169 kg	Number of System 1 Bodies
Max Length	1500 mm	
Max Depth	30 m	Total Energy8000Storage Capacity

Wave Energy Conversion Method Surface Riding WEC

Average Recharge Power 36 Watt